

# 7.1. MALLIAVIN GRADIENT AND INTEGRATION BY PARTS ON WIENER SPACE

$$\Omega = C([0,1], \mathbb{R}^d) \quad \text{with sup-norm}$$

$$P = \text{Wiener measure (start in 0)}$$

$$B_+(w) = w(t) \quad \text{canonical BM}$$

DEF.  $F: \Omega \rightarrow \mathbb{R}$  Fréchet differentiable at  $w$

$\Leftrightarrow \exists$  contin. linear form  $d_w F: \Omega \rightarrow \mathbb{R}$ :

$$\|F(w+h) - F(w) - (d_w F)(h)\|_{\mathbb{R}} = o(\|h\|_{\Omega}) \quad \forall h \in \Omega$$

In this case there exist directional derivatives

$$\frac{\partial F}{\partial h}(w) = \lim_{\varepsilon \downarrow 0} \frac{F(w+\varepsilon h) - F(w)}{\varepsilon} = (d_w F)(h) \quad \forall h \in \Omega$$

PROBLEM:  $X_t$  sol. of s.d.e. is in general not Fréchet-diff.

$$\text{E.g. } F = \int_0^1 B_t^1 dB_t^2 : \frac{\partial F}{\partial h} = \int_0^1 h_t^1 dB_t^2 + \int_0^1 B_t^1 dh_t^2 \quad \text{formal derivative}$$

NOT CONTIN. in  $h$  w.r.t. sup-norm!  $\nabla$

$$H = \{h: [0,1] \rightarrow \mathbb{R}^d \mid h(0)=0, h \text{ abs. contin. with } h' \in L^2\}$$

$$(h, g)_H = \int_0^1 h'_t g'_t dt$$

CAMERON-MARTIN. SPACE ( $\rightarrow$  tangent space)

### DEF. (MALLIAVIN GRADIENT)

1) For  $F \in C_b^1(\Omega)$  and  $\omega \in \Omega$  define  $(D^H F)(\omega) \in H$  via

$$(*) \quad (D^H F)(\omega), h)_H = \frac{\partial F}{\partial h}(\omega) = (d_\omega F)(h) \quad \forall h \in H,$$

i.e.,  $D^H F$  is gradient of  $F$  w.r.t. metric  $(\cdot, \cdot)_H$

$$2) \quad (D_t F)(\omega) := \frac{d}{dt} (D^H F)(\omega) \in L^2([0,1], \mathbb{R}^d)$$

EXAMPLES 1) Brownian motion:  $\boxed{(D_t B_s^i)(\omega) = e_i \cdot \mathbb{I}_{(0,s)}(t)}$

2) Wiener integrals:  $F = \int_0^1 g \cdot dB$ ,  $g \in C^1([0,1], \mathbb{R}^d)$

$$\Rightarrow \boxed{(D_t F)(\omega) = g(t)}$$

THEOREM (INTEGRATION BY PARTS, BISMUT)

$$F \in C_b^1(\Omega), G_t \in \mathcal{L}_a^2(\Omega \times [0,1], \mathbb{P} \otimes dt), H_t = \int_0^t G_s ds$$

$$(**) \quad \underbrace{E \left[ \int_0^1 D_t F \cdot G_t dt \right]}_{(DF, G)_{L^2(\mathbb{P} \otimes \lambda)}} = E \left[ \overbrace{(D_t^H F, H)_H}^{=2_H F} \right] = E \left[ F \int_0^1 G_t dB_t \right]_{(F, \int_0^1 G_t dB)_{L^2(\mathbb{P})}}$$

REMARK: Infinitesimal version of Girsanov theorem:

$$B = (B_t)_{0 \leq t \leq 1} \text{ identity map on } \Omega$$

$$E[F(B + \varepsilon H)] = E[F(B) \cdot Z_t^\varepsilon] \quad \text{where}$$

$$Z_t^\varepsilon := \exp \left( \varepsilon \int_0^t G_s \cdot dB_s - \frac{\varepsilon^2}{2} \int_0^t |G_s|^2 ds \right)$$

Derivative w.r.t.  $\varepsilon \Rightarrow$  Claim

PROOF: 1) Assume  $G$  is bounded. Then by Novikov,  $Z_t^\varepsilon$  is a martingale, and by Girsanov,

$$E \left[ \frac{F(B+\varepsilon H) - F(B)}{\varepsilon} \right] = E \left[ F(B) \frac{Z_1^\varepsilon - 1}{\varepsilon} \right]$$

$\varepsilon \downarrow 0$ : r.h.s.  $\rightarrow E \left[ F(B) \int_0^1 G dB \right]$

since  $\frac{Z_1^\varepsilon - 1}{\varepsilon} = \int_0^1 Z_t^\varepsilon G dB \xrightarrow{\varepsilon \downarrow 0} \int_0^1 G dB$  in  $L^2(P)$

$\rightarrow 1$  in  $L^2(P \otimes \lambda)$  (Exercise)  
 $dZ^\varepsilon = \varepsilon Z^\varepsilon G dB$

l.h.s. =  $E \left[ \frac{1}{\varepsilon} \int_0^\varepsilon (\partial_H F)(B+sH) ds \right] \xrightarrow{\text{Leb.}} E \left[ (\partial_H F)(B) \right]$

$\rightarrow (\partial_H F)(B)$  as  $s \downarrow 0$

since  $F \in C_b^1(\mathbb{R})$

2) Since both sides of (\*\*) are continuous in  $G$  w.r.t. the  $L^2(P \otimes \lambda)$  norm, the equation extends to all  $G \in L^2_a(P \otimes \lambda)$ . □

# A FIRST APPLICATION: SKOROKHOD INTEGRAL

$$F \mapsto (D_t F)_{0 \leq t \leq 1}$$

$$D: C_b^1(\Omega) \subseteq L^2(\Omega, P) \rightarrow L^2(\Omega \times [0, 1], P \otimes \lambda)$$

is a densely defined linear operator. Define

$$\delta: \text{Dom}(\delta) \subseteq L^2(P \otimes \lambda) \rightarrow L^2(P)$$

as the adjoint operator (divergence). Then:

$$G_t \in \mathcal{L}_a^2(P \otimes \lambda) \xrightarrow{\text{Bismut}} G_t \in \text{Dom}(\delta), \quad \delta(G) = \int_0^1 G_t dB_t$$

Hence  $\delta$  is an extension of the Itô integral to

not necessarily adapted processes  $G \in L^2(P \otimes \lambda)$  !

EXAMPLE  $G_t$  adapted + bounded,  $F \in C_b^1(\Omega)$

$$\Rightarrow (F \cdot G_t)_{0 \leq t \leq 1} \in \text{Dom}(\delta)$$

$$\text{Skorokhod integral: } \delta(FG) = F \delta(G) - \int_0^1 D_t F G_t dt$$

"product rule for divergence operator"

## DEFINITION OF MALLIAVIN GRADIENT II (CLOSURE) <sup>7.6</sup>

$\mathbb{D}^{1,p} :=$  closure of  $C_b^1(\Omega) \subseteq L^p(\Omega; P)$  w.r.t. norm

$$\|F\|_{1,p} := \left[ E[|F|^p + \|D^H F\|_H^p] \right]^{\frac{1}{p}}, \quad p \in [1, \infty)$$

THEOREM 1)  $\exists!$  extension of  $D^H$  to a contin. lin. op.

$$D^H: \mathbb{D}^{1,p} \subseteq L^p(\Omega; P) \rightarrow L^p(\Omega \rightarrow H; P)$$

2) The Itô integration by parts formula holds for all  $F \in \mathbb{D}^{1,2}$ .

## THEOREM (PRODUCT- AND CHAIN RULE)

1)  $F, G \in \mathbb{D}^{1,2} \cap L^\infty \Rightarrow F \cdot G \in \mathbb{D}^{1,2}$  with

$$D(F \cdot G) = F DG + G DF$$

2)  $F_1, \dots, F_m \in \mathbb{D}^{1,2}$ ,  $\phi \in C_b^1(\mathbb{R}^m) \Rightarrow \phi(F_1, \dots, F_m) \in \mathbb{D}^{1,2}$  with

$$D \phi(F_1, \dots, F_m) = \sum_{i=1}^m \frac{\partial \phi}{\partial x_i}(F_1, \dots, F_m) DF_i$$

## 7.2. ITO REPRESENTATION THEOREM AND CLARK-OCONE FORMULA

7.7

$\mathcal{F}_t = \sigma(B_s \mid 0 \leq s \leq t)$  Brownian filtration

THEOREM (ITO) For any  $F \in L^2(\Omega, \mathcal{F}_1, P)$  there exists a unique  $G \in L^2_a(0,1)$  s.t.

$$F = E[F] + \int_0^1 G_s dB_s \quad \text{P-a.s.}$$

COROLLARY For any  $L^2$ -bounded  $(\mathcal{F}_t)$ -martingale  $(M_t)_{0 \leq t \leq 1}$  there exists a unique  $G \in L^2_a(0,1)$  s.t.

$$M_t = M_0 + \int_0^t G_s dB_s \quad \text{P-a.s.} \quad \forall t \in [0,1].$$

In particular: Every  $(\mathcal{F}_t)$ -martingale has a continuous modification!

REMARK: Assumption  $\mathcal{F}_t = \mathcal{F}_t^{B,P}$  is crucial.

Identification of  $G_t$ ?

THEOREM (CLARK-OCONE) For  $F \in \mathcal{D}^{1,2}$ ,

$$F = E[F] + \int_0^1 E[D_t F | \mathcal{F}_t] dB_t \quad \text{P-a.s.}$$

EXAMPLE: Look-back-option:  $F = \max_{0 \leq t \leq 1} B_t$

Fact: For P-a.e.  $\omega$  there ex. a unique  $T(\omega) \in [0, 1]$  s.t.  $F = B_T$ .

$$F \in \mathcal{D}^{1,2} \text{ with } D_t F(\omega) = \mathbb{I}_{[0, T(\omega)]}(t).$$

$$E[D_t F | \mathcal{F}_t](\omega) = P[T > t | \mathcal{F}_t](\omega)$$

$$= P\left[ \max_{t \leq s \leq 1} B_s \geq M_t \mid \mathcal{F}_t \right](\omega) = P\left[ \max_{t \leq s \leq 1} (B_s - B_t) \geq M_t(\omega) - B_t(\omega) \right]$$

$$\parallel \\ B_t + (B_s - B_t)$$

$$\sim \max_{0 \leq s \leq 1-t} B_s \sim |B_{1-t}| \sim \sqrt{1-t} \cdot |B_1|$$

$$= 2 \Phi\left(\frac{M_t(\omega) - B_t(\omega)}{\sqrt{1-t}}\right), \quad \Phi(x) = \frac{1}{\sqrt{2\pi}} \int_x^\infty e^{-y^2/2} dy$$

Clark-Ocone

$$\implies M_1 = \sqrt{\frac{2}{\pi}} + \int_0^1 2 \Phi\left(\frac{M_t - B_t}{\sqrt{1-t}}\right) dB_t$$



### 7.3. FIRST APPLICATIONS TO SDE

7.9

THEOREM (Malliavin derivative of  $H^1_0$  integrals)

Suppose  $G_s \in L^2_a(\mathbb{P} \otimes \lambda_{[0,1]})$  with  $G_s \in \mathcal{D}^{1,2}$  for all  $s \in [0,1]$

and  $(\omega, t, s) \mapsto (D_t G_s)(\omega) \in L^2(\Omega \times [0,1]^2, \mathbb{P} \otimes \lambda^2)$ .

Then  $\int_0^u G_s dB_s \in \mathcal{D}^{1,2}$  for all  $u \in [0,1]$  and

$$\left\| D_t \int_0^u G_s dB_s = \int_0^u D_t G_s \cdot dB_s + G_t \cdot I_{(0,u)}(t) \right\| \mathbb{P} \otimes \lambda\text{-a.s.}$$

$$\boxed{(*) \quad dX_t = \sum_{j=1}^d \sigma_j(X_t) dB_t^j + b(X_t) dt}$$

THEOREM If  $\sigma_j, b: \mathbb{R}^n \rightarrow \mathbb{R}^n$  are Lipschitz then  $X_t^i \in \mathcal{D}^{1,p}$  for all  $1 \leq i \leq n$  and  $1 \leq p < \infty$  with Malliavin derivative

$$D_r^k X_t = \begin{cases} \sigma_k(X_r) + \sum_j \int_r^t \sigma_j'(X_s) D_r^k X_s dB_s^j + \int_r^t b_j'(X_s) D_r^k X_s ds & \text{for } t \geq r, \\ 0 & \text{for } t < r. \end{cases}$$

## Application 1: Variation of the initial condition

$$\xi_t^x = \text{flow of sde (*)}$$

$$Y_t^x = \xi_t^x(x) \text{ derivative flow}$$

is fundamental solution of linear sde

$$(**) \quad dY_t = \sum_j \sigma_j'(\xi_t) Y_t dB_t^j + b'(\xi_t) Y_t dt$$

$$Y_0 = \underline{I}$$

COROLLARY  $D_r^k \xi_t = Y_t Y_r^{-1} \sigma_k'(\xi_r) \mathbb{I}_{\{t \geq r\}}$

Conversely: If  $\sigma$  is strictly elliptic then

$$Y_t = D_r \xi_t \sigma(\xi_r)^{-1} Y_r \quad \forall r \leq t$$

$$\Rightarrow Y_t = \frac{1}{t} \int_0^t D_r \xi_t \sigma(\xi_r)^{-1} Y_r dr$$

COROLLARY (BISMUT-ELWORTHY) For all  $t > 0$ ,  $f \in C_b^1(\mathbb{R}^n)$  and  $x \in \mathbb{R}^n$ :

$$d_x E[f(\xi_t^x)] = \frac{1}{t} E\left[ f(\xi_t^x) \int_0^t \sigma(\xi_r^x)^{-1} Y_r^x dB_r \right]$$

Remark: R.h.s. does not involve derivatives!

→ Numerical schemes for computing l.h.s.

Application 2: Variation of the drift coefficient

$$dX_t^\varepsilon = \sum_j \sigma_j(X_t^\varepsilon) dB_t^j + b(\varepsilon, X_t^\varepsilon) dt, \quad X_0^\varepsilon = x$$

$\varepsilon \in (-\delta, \delta)$ ,  $\sigma$  strictly elliptic,  $X_t := X_t^0$

FACT:  $b: (-\delta, \delta) \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $\sigma_j: \mathbb{R}^n \rightarrow \mathbb{R}^n \in C_b^2$

⇒  $\exists V_t := \frac{\partial}{\partial \varepsilon} X_t^\varepsilon \Big|_{\varepsilon=0}$ ,  $V_0 = 0$ , and

$$dV_t = \sum_j \sigma_j'(X_t) V_t dB_t^j + b'(0, X_t) V_t dt + \frac{\partial b}{\partial \varepsilon}(0, X_t) dt$$

COROLLARY 1)  $V_t = \int_0^t (D_r X_t) \sigma(X_r)^{-1} \frac{\partial b}{\partial \varepsilon}(0, X_r) dr$

2)  $\frac{\partial}{\partial \varepsilon} E[f(X_t^\varepsilon)] \Big|_{\varepsilon=0} = E[f(X_t) \int_0^t \sigma(X_r)^{-1} \frac{\partial b}{\partial \varepsilon}(0, X_r) dB_r]$

Proof: 1) Variation of constants  $\Rightarrow$

$$\begin{aligned} V_t &= \int_0^t Y_t Y_r^{-1} \frac{\partial b}{\partial \varepsilon}(0, X_r) dr \\ &= \int_0^t (\mathcal{D}_r X_t) \sigma(X_r)^{-1} \frac{\partial b}{\partial \varepsilon}(0, X_r) dr \end{aligned}$$

$$2) \frac{\partial}{\partial \varepsilon} E[f(X_t^\varepsilon)] \Big|_{\varepsilon=0} = E[f'(X_t) V_t] = \text{r.h.s.}$$

by 1) and the Bismut integration by parts identity.  $\square$

Further important applications of Malliavin calculus:

- Existence of (smooth) densities for the distributions of solutions of s.d.e.
- Stochastic proof of Hörmander's theorem (Hypoellipticity)

## 5.5 EXISTENCE & SMOOTHNESS OF DENSITIES

$$(*) \quad dX_t = b(X_t)dt + \sigma(X_t)dB_t, \quad X_0 = x$$

$P_t(x, \cdot) = P_0 X_t^{-1}$  absolutely continuous?

### THEOREM 5.21 (Malliavin's lemma)

Let  $\mu$  be a finite measure on  $\mathcal{B}(\mathbb{R}^n)$ .

1) If there exists  $C \in \mathbb{R}_+$  s.t.

$$|\int \nabla f d\mu| \leq C \cdot \sup |f| \quad \forall f \in C_b^\infty(\mathbb{R}^n)$$

then  $\mu \ll \lambda^n$  with density  $\frac{d\mu}{dx} \in L^{\frac{n}{n-1}}(\mathbb{R}^n, dx)$ .

2) If for any multi-index  $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{Z}_+^n$ , there exists  $C_\alpha \in \mathbb{R}_+$  s.t.

$$|\int \partial^\alpha f d\mu| \leq C_\alpha \cdot \sup |f| \quad \forall f \in C_b^\infty(\mathbb{R}^n)$$

then  $\frac{d\mu}{dx} \in C^\infty(\mathbb{R}^n)$ .

Rem. Compare to Sobolev embedding theorem!

## Application to SDE (\*) :

GOAL:  $|\int \nabla f(b) p_t(x, ds)| = |E[\nabla f(x_t)]| \leq C \cdot \sup |f|$

IDEA ( $d=n=1$ ):

$$D_r f(x_t) = f'(x_t) D_r x_t = f'(x_t) Y_t Y_r^{-1} \sigma(x_r) \mathbb{I}_{\{r \leq t\}}$$

If  $\sigma$  is non-degenerate, this implies

$$f'(x_t) = \frac{1}{t} \int_0^t D_r f(x_t) \sigma(x_r)^{-1} Y_r dr Y_t^{-1} = \frac{1}{t} (D_f^H(x_t), H)_H Y_t^{-1}$$

where  $H_s = \int_0^{s \wedge t} \sigma(x_r)^{-1} Y_r dr$ . By taking expectations on both sides and integrating by parts, one can prove:

THEOREM 5.22 (Absolute continuity of transition densities)

Suppose  $\sigma, b \in C_b^1$  and  $n$ , and  $\sigma(x) \geq \varepsilon I_n \forall x$  with  $\varepsilon > 0$ .

Then  $p_t(x, \cdot) \ll \lambda^n$  for any  $t > 0$ .

EXTENSIONS: • Higher regularity / smoothness by repeated i.b.p.

• Degenerate diffusion coefficient: Absolute continuity / smoothness under Hörmander's condition.