OrnsteinUhlenbeck1D with output

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1 SDE approximation by Euler scheme

We simulate a one dimensional Ornstein-Uhlenbeck process by using an Euler approximation of the solution to the corresponding stochastic differential equation.

In [9]: # Euler-Maryuama Approximation for solution of SDE $dX_t = -gamma X_t dt + sigma dB_t$

```
import numpy as np
# makes numpy routines and data types available as np.[name ouf routine or data type]
import matplotlib.pyplot as plt
# makes plotting command available as plt.[name of command]
x0 = 5.
# initial value at time t=0
sigma = 2.
# volatility
gamma = .5
# friction coefficient
tmax = 5.
# simulation of process from time 0 to tmax
stepslist = [10,100,1000,10000]
# produce simulations with step numbers chosen from steplist
for steps in stepslist:
    h = tmax/steps
    # stepsize for time discretization
    std = np.sqrt(h)
    # standard deviation for the distribution of each step
    k = 100
    # number of samples that will be simulated
    noise = np.random.randn(steps,k)*std
    # create a steps times k dimensional matrix of normal random numbers
    # with variance h
```

```
sde = np.ones((steps,k))
sde = sde*x0
# initialize the array sde with the initial condition x0
for n in range(steps-1):
    sde[n+1] = sde[n]-gamma*h*sde[n]+sigma*noise[n]
t = np.arange(0,steps,1)*h
# creates vector of time points
plt.figure(figsize=(10,6), dpi=80)
# sets size of plot
plt.plot(t,sde,linewidth=0.3)
# produces a plot of the sample solutions in the components of sde
# versus t with thin lines
plt.show()
# output of plot
```









After some time the process seems to approach an equilibrium distribution.

2 Solution flow of Ornstein-Uhlenbeck SDE

We now simulate simultaneously the solutions starting from different initial conditions where the same noise random variables are applied in each case.

```
In [7]: # Euler approximation for flow of SDE dX_t = -gamma X_t dt + sigma dB_t
import numpy as np
# makes numpy routines and data types available as np.[name ouf routine or data type]
import matplotlib.pyplot as plt
# makes plotting command available as plt.[name of command]
sigma = 2.
# volatility
gamma = .5
# friction coefficient
tmax = 5.
# simulation of process from time 0 to tmax
stepslist = [10,100,1000,10000]
# produce simulations with step numbers chosen from steplist
for steps in stepslist:
```

```
h = tmax/steps
# stepsize for time discretization
std = np.sqrt(h)
# standard deviation for the distribution of each step
k = 10
# number of initial values to be considered
x0 = np.linspace(-5.,5.,k)
# simulate solutions for this list of initial values
noise = np.random.randn(steps)*std
\ensuremath{\textit{\#}} create a steps dimensional vector of normal random numbers with variance h
sde = np.zeros((steps,k))
sde[0] = x0
# initialize the array sde with the initial conditions in x0
for n in range(steps-1):
    sde[n+1] = sde[n]-gamma*h*sde[n]+sigma*noise[n]
t = np.arange(0,steps,1)*h
# creates vector of time points
plt.figure(figsize=(10,6), dpi=400)
# sets size of plot
plt.plot(t,sde,linewidth=0.3)
# produces a plot of the sample solutions in the components of sde
# versus t with thin lines
plt.show()
# output of plot
```







We observe that the solutions for different initial values approach each other ("loss of memory of initial condition").

In []: