

Multilevel Sampling

Monte Carlo Methods for sequences of probability measures

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1 INTRODUCTION

THE PROBLEM : $\mu_0, \mu_1, \dots, \mu_k$ probability measures on state space S .

E.g.: $S = V$ vertex set of graph, $S = \{0, 1\}^V$, $S = \mathbb{R}^d$, $S = C([0, 1], \mathbb{R}^d)$.

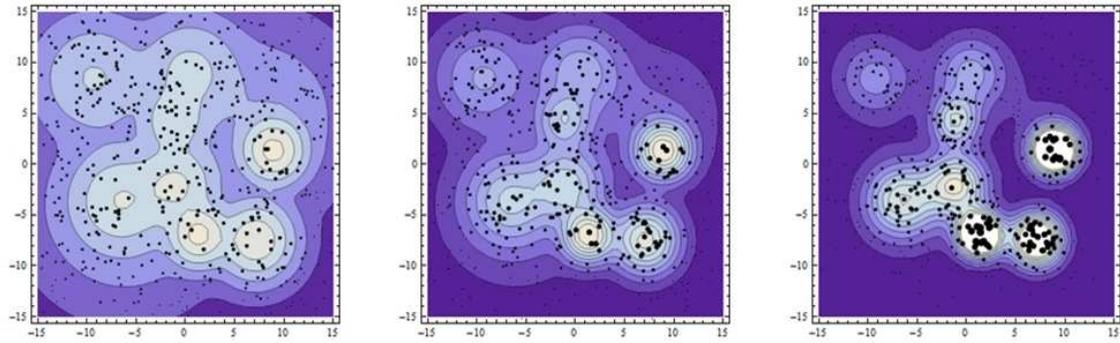
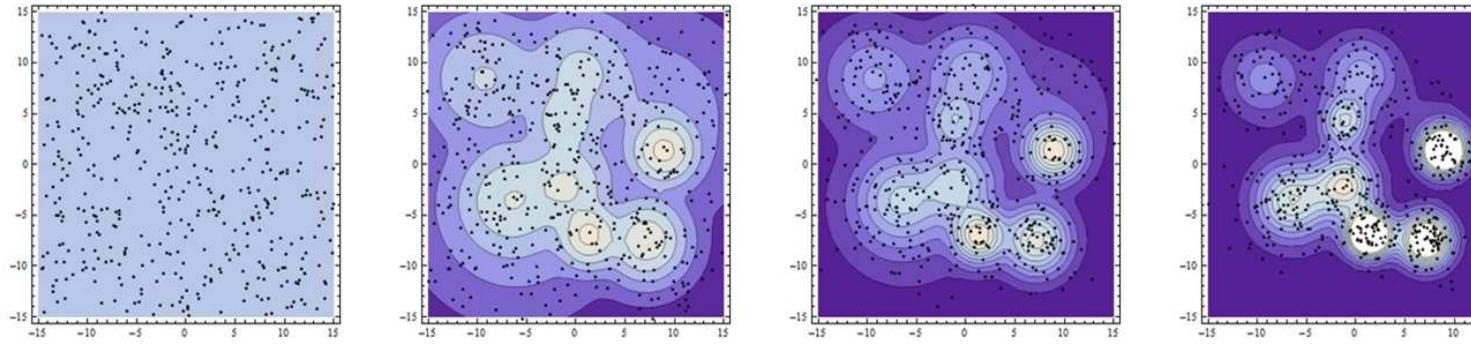
$$\mu_t(dx) = \mu_t(x) \nu(dx); \quad \mu_t(x) = \frac{1}{Z_t} \cdot \exp(-U_t(x))$$

- ν reference measure
- $U_t : S \rightarrow \mathbb{R}$ known/can be computed
- Z_t unknown normalization constant/partition function

AIM : Sequential Monte Carlo Estimation/Approximation of

$$\langle f, \mu_t \rangle := \int_S f(x) \mu_t(dx), \quad t = 0, 1, \dots, k,$$

for appropriate class of functions $f : S \rightarrow \mathbb{R}$.



MOTIVATION:

- *Dynamical*: E.g. non-linear filtering, Hidden Markov Models

X_0, X_1, \dots, X_k Markov chain (*unobserved signal*)

Y_0, Y_1, \dots, Y_k noisy perturbations (*observation*)

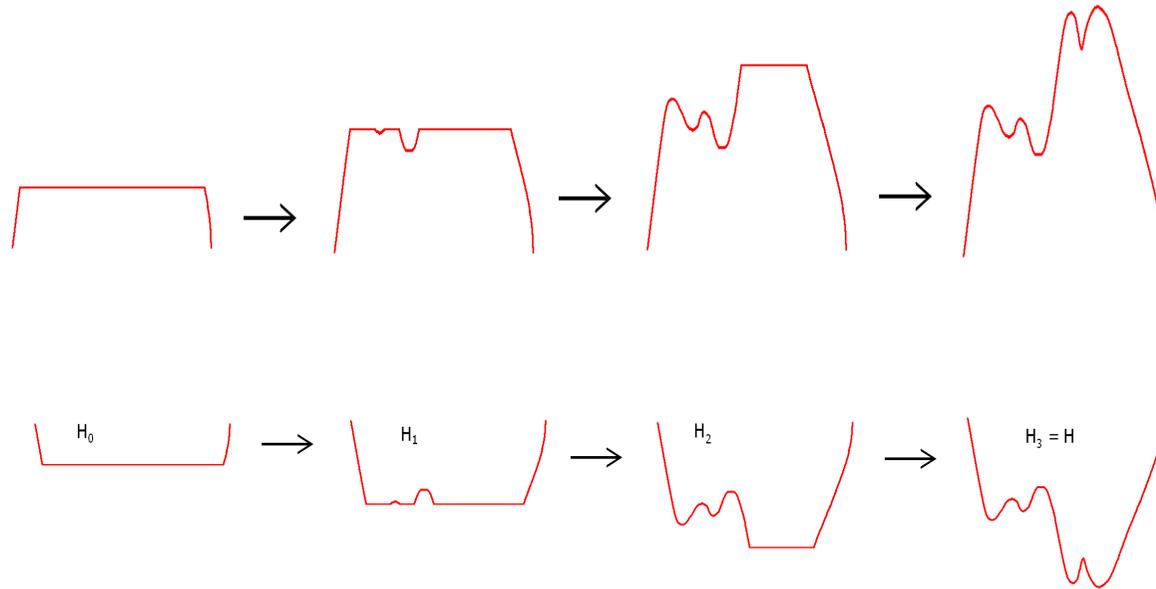
μ_t = conditional distribution of X_t given Y_0, \dots, Y_t

↪ **Particle filters**, see e.g. [Doucet, de Freitas, Gordon: *Sequential MC methods in practice*].

- *Static*: $\mu(dx) = Z^{-1} \exp(-U(x)) \nu(dx)$ **Target distribution**
 - difficult to simulate because of multimodality, metastable states, singular density,...
 - ↪ choose interpolation $\nu = \mu_0, \mu_1, \dots, \mu_k = \mu$, e.g. such that $\mu_k(x)/\mu_{k-1}(x) \leq 2$
 - ↪ “*resolution of singularity*” by “*homotopy method*”.

EXAMPLES: Choice of interpolating probability measures

- *Annealing* : $\mu_t(x) \propto \exp(-\beta_t U(x))$, β_t cooling schedule, $\beta_0 = 0$, $\beta_k = 1$.
- *Equi-Energy Sampling* : $\mu_t(x) \propto \exp(-\beta_t \cdot \max(U(x), E_t))$

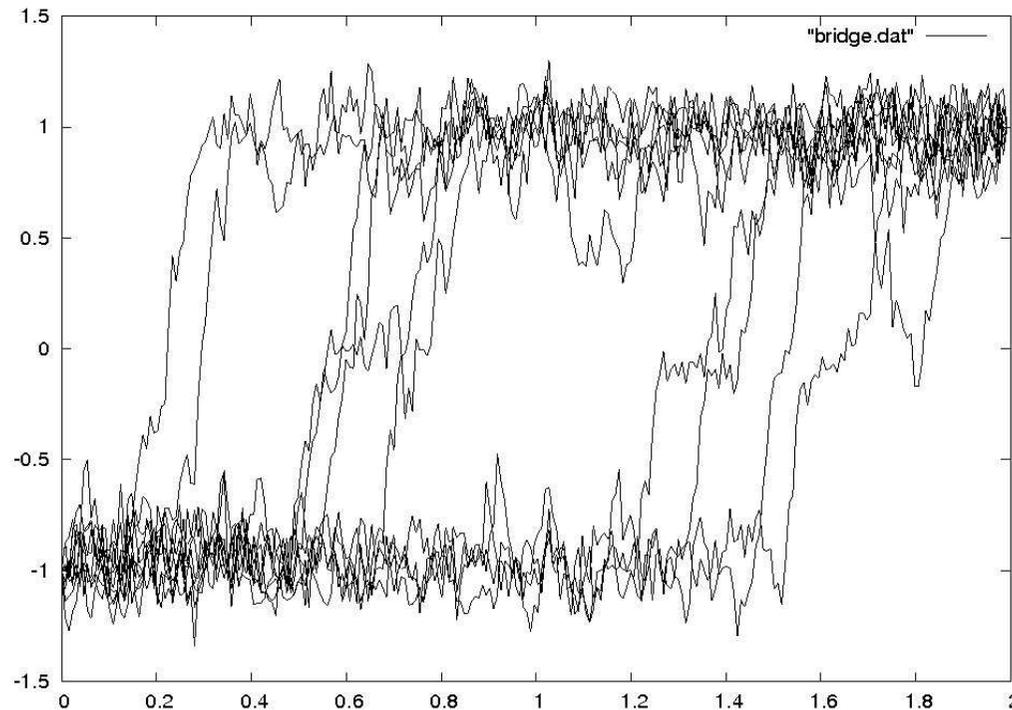


- *Spatial Coarse Graining* :

e.g. μ measure on $S = C([0, 1], \mathbb{R}^d)$, μ_t approximation on

$$S_k = \{\omega : [0, 1] \rightarrow \mathbb{R}^d : \omega \text{ linear on } [(k-1)2^{-t}, k2^{-t}] \text{ for any } k\}.$$

↪ **Transition Path Sampling**



MARKOV CHAIN MONTE CARLO :

- *Energy Landscape*: $U : S \rightarrow \mathbb{R}_+$, $\mu_t(x) \propto \exp(-\beta_t \cdot \max(U(x), E_t))$
- *Markov Chain Monte Carlo Approach (MCMC)*:
 - Explore energy landscape by reversible stochastic dynamics: (X^i)
Markov chain with transition density $p_t(x, y)$ s.t.

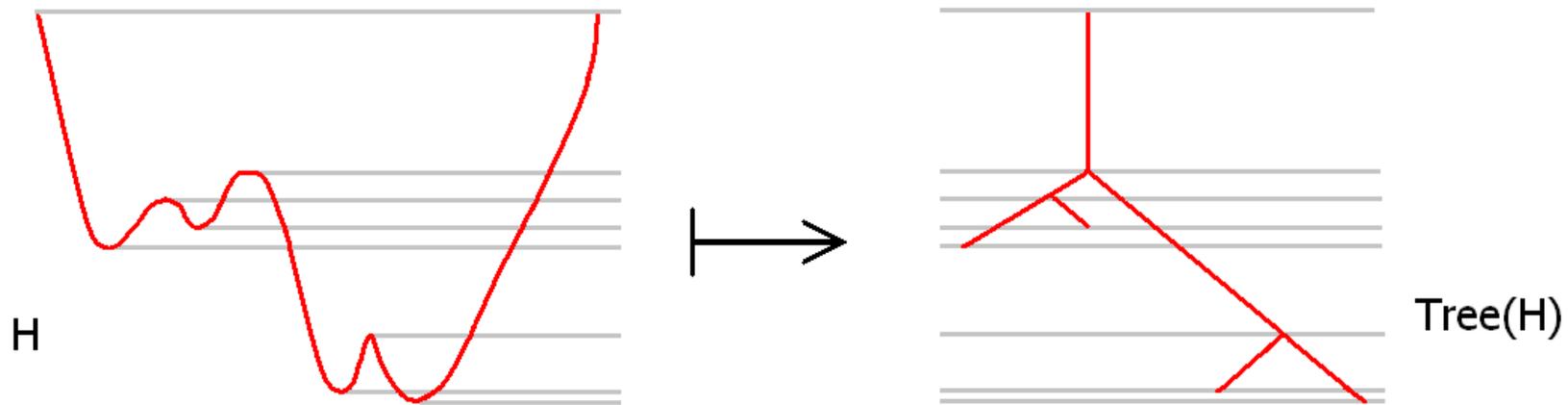
$$\mu_t(x) p_t(x, y) = \mu_t(y) p_t(y, x) \quad \text{Detailed Balance}$$

- Estimate μ_t by $\hat{\mu}_t = \sum_{i=1}^{\lambda_t} \delta_{X^i}$.
- Example [Metropolis et al. (1953), Hastings (1971)]

$$p_t(x, y) = q(x, y) \cdot \min \left(\frac{\mu_t(y)q(y, x)}{\mu_t(x)q(x, y)}, 1 \right), \quad q \text{ proposal density}$$

METASTABILITY PROBLEM :

- Local energy minima \rightsquigarrow metastable states \rightsquigarrow traps for Markov chain
- *Simulated Annealing with logarithmic cooling schedule*: Cool down so slowly that Markov chain escapes traps.
 \rightsquigarrow not feasible in practice !
- *Realistic approach*: Cool down much faster.
 \rightsquigarrow Markov chain eventually gets trapped



DISCONNECTIVITY TREE OF ENERGY FUNCTION:

S \rightarrow Disconnectivity tree \mathbb{T}
 Energy function $U : S \rightarrow \mathbb{R}_+$ \rightarrow Height function $h : \mathbb{T} \rightarrow \mathbb{R}_+$
 Reference measure ν \rightarrow Density of states $\Omega(dx)$ on \mathbb{T}
 μ_t \rightarrow $\bar{\mu}_t(dx) \propto e^{-\beta_t h(x)} \Omega(dx)$

- As t increases, the Markov chain gets trapped in deeper branches of the tree.
- The state space effectively splits into an increasing number of components (metastable states)

KEY PROBLEM:

- Are there feasible Markov chain based methods for Monte Carlo integral estimation w.r.t. the sequence μ_t ($t = 0, 1, \dots, k$) in spite of trapping ?
- When do they apply ?
- Any quantitative error bounds for simple models ?

2 MONTE CARLO METHODS FOR SEQUENCES

- *Importance Sampling*
- *Markov Chain Monte Carlo (MCMC)* [Metropolis et al. 1953]
- *Simulated Annealing* [Kirkpatrick, Gelatt, Vecchi 1982]
- *Simulated Tempering* [Marinari, Parisi 1992]
- *Parallel Tempering* [Geyer 1991]
- *Equi-Energy Sampler* [Kou, Zhou, Wong 2006]
- *Sequential Monte Carlo Samplers* [Del Moral, Doucet, Jasra 2006]

REFERENCE: Liu, *Monte Carlo Methods in Scientific Computing*

IMPORTANCE SAMPLING:

ALGORITHM (Importance Sampling, Umbrella Sampling).

- Sample X^i ($1 \leq i \leq N$) i.i.d. $\sim \nu$
- For $t := 0, 1, \dots, k$ do
 - Compute importance weights $w_t^i := \mu_t(X^i) / \sum_{j=1}^N \mu_t(X^j)$
 - Estimate μ_t by $\hat{\mu}_t^N := \sum_{i=1}^N w_t^i \delta_{X^i}$

Remarks.

- Computation of importance weights can be implemented sequentially
- Law of Large Numbers $\Rightarrow \langle f, \hat{\mu}_t^N \rangle$ is asymptotically unbiased estimator for $\langle f, \mu_t \rangle$
- $\text{Var}(\langle f, \hat{\mu}_t^N \rangle) = O(N^{-1/2})$ for any $f \in L^2(\mu_t)$

Drawback.

- Variance can be very large if $\sup_x \mu_t(x) / \inf_x \mu_t(x)$ is large.

MCMC: t fixed, λ_t nr. of steps, $p_t(x, y)$ transition density, DB w.r.t. μ_t

ALGORITHM (Independent Monte Carlo Markov Chains).

- Sample X_t^i ($1 \leq i \leq N$) i.i.d. $\sim \nu$
- For $m := 1$ to λ_t do
 - Sample Y_t^i condit. independent $\sim p_t(X_t^i, \cdot)$; replace X_t^i by Y_t^i .
- Estimate μ_t by $\hat{\mu}_t^N := N^{-1} \sum_{i=1}^N \delta_{X_t^i}$

TWO ERRORS.

$$\hat{\mu}_t^N - \mu_t = \underbrace{(\hat{\mu}_t^N - \nu_t)}_{\text{MC error}} + \underbrace{(\nu_t - \mu_t)}_{\text{Deviation from equilibrium}}, \quad \nu_t = \text{distrib. of chain after } \lambda_t \text{ steps}$$

- $E \left[\left| \langle f, \hat{\mu}_t^N \rangle - \langle f, \nu_t \rangle \right|^2 \right] = N^{-1} \cdot \text{Var}(f; \nu_t)$
- $\langle f, \nu_t \rangle - \langle f, \mu_t \rangle \rightarrow 0$ as $\lambda_t \rightarrow \infty$ if ergodicity holds.

QUANTITATIVE BOUNDS FOR DISTANCE FROM EQUILIBRIUM:

a) W.r.t. χ^2 divergence:

$$\chi^2(\nu_t|\mu_t) = \sup_{\langle f^2, \mu_t \rangle \leq 1} |\langle f, \nu_t \rangle - \langle f, \mu_t \rangle|^2 \leq e^{-\lambda_t/C_t} \cdot \chi^2(\nu|\mu_t)$$

$$C_t^{-1} = \inf_{\langle f, \mu_t \rangle = 0} \frac{\mathcal{E}_t(f, f)}{\langle f^2, \mu_t \rangle} \quad \text{Spectral gap,}$$

$$\mathcal{E}_t(f, f) = \int \int \mu_t(x) p_t(x, y) (f(y) - f(x))^2 \nu(dx) \nu(dy) \quad \text{Dirichlet form}$$

b) W.r.t. Relative Entropy / Kullback-Leibler divergence: (Chain in cont. time)

$$H(\nu_t|\mu_t) = \int \frac{d\nu_t}{d\mu_t} \log \frac{d\nu_t}{d\mu_t} d\mu_t \leq e^{-\lambda_t/\gamma_t} \cdot H(\nu|\mu_t)$$

$$\gamma_t^{-1} = \inf_{\langle f^2, \mu_t \rangle = 1} \frac{\mathcal{E}_t(f, f)}{\langle f^2 \log f^2, \mu_t \rangle} \quad \text{Logarithmic Sobolev constant}$$

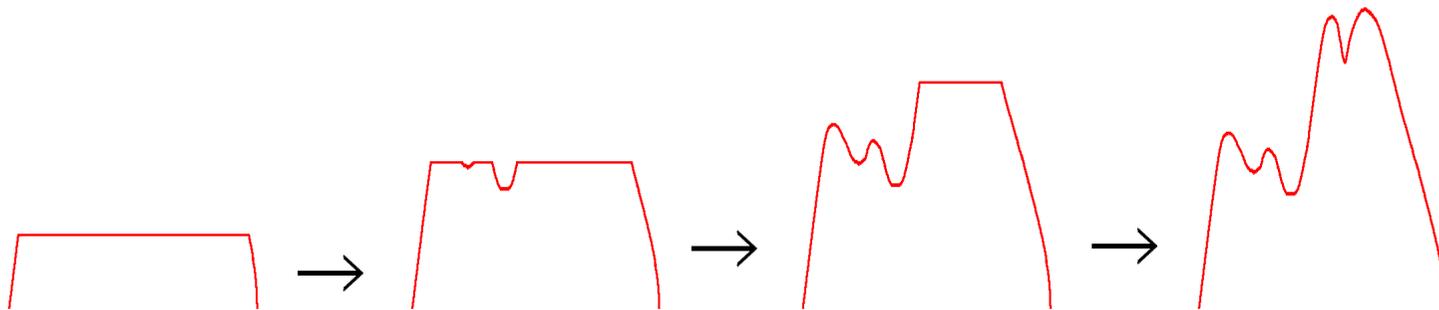
REFERENCE: Peres, *Markov Chains and mixing times*

SIMULATED TEMPERING:

- MCMC on $S \times \{0, 1, \dots, k\}$ with stationary distribution

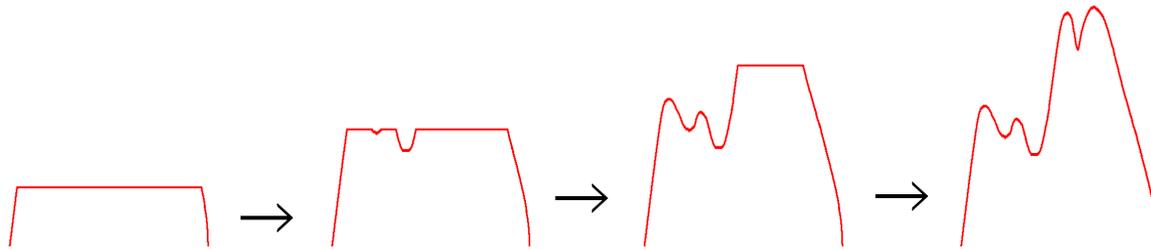
$$\bar{\mu}(x, t) \propto a_t \cdot \exp(-U_t(x)), \quad \bar{\mu}(\cdot | t) = \mu_t.$$

- $a_t = Z_t^{-1} \Rightarrow \bar{\mu}(S, t) = (k + 1)^{-1}$ Uniform distribution in t
- In practice use estimate \hat{Z}_t



PARALLEL TEMPERING: MCMC on $\mathcal{S}^{\{0,1,\dots,k\}}$ with equilibrium

$$\tilde{\mu}(x_0, x_1, \dots, x_k) = \prod_{t=0}^k \mu_t(x_t).$$



Transition step.

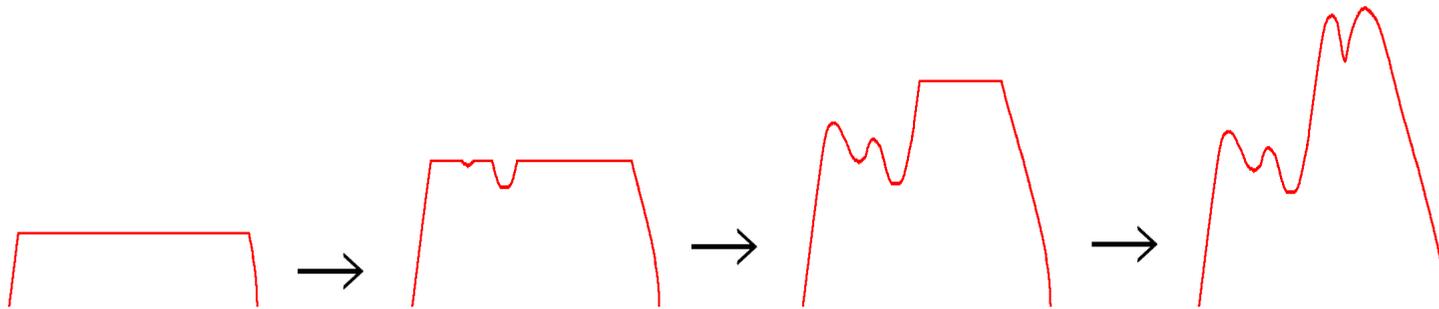
- Sample $t \sim \text{Unif}\{0, 1, \dots, k\}$
- *With probability* $1 - \varepsilon$: Sample $Y_t \sim p_t(X_t, \cdot)$; replace X_t by Y_t .
- *With probability* ε : Sample $U \sim \text{Unif}(0, 1)$;
if $t > 0$ and $U < \min\left(1, \frac{\mu_t(X_{t-1})\mu_{t-1}(X_t)}{\mu_t(X_t)\mu_{t-1}(X_{t-1})}\right)$ then **exchange** X_t and X_{t-1} .

[Madras and Zheng], [Bhatnagar and Randall]

- Rapid Mixing on Mean Field Ising Model

$$C_t = O(N^\alpha), \quad N = \text{number of spins},$$

- BUT: Torpid Mixing on Mean-Field Potts Model.

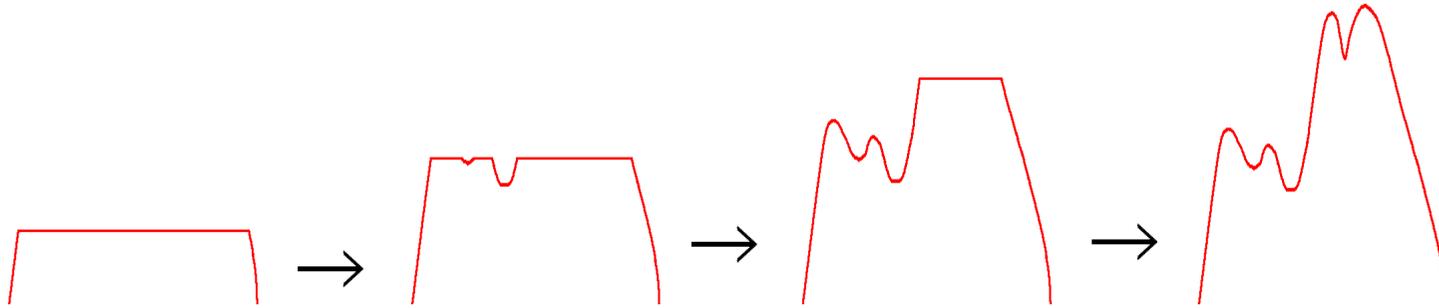


EQUI-ENERGY SAMPLER: [Kou, Zhou, Wong, *Annals of Statistics* 2006]

ALGORITHM (EE-Sampler). Fix $\lambda_0, \lambda_1, \dots, \lambda_k \in \mathbb{N}$, $\delta_0, \delta_1, \dots, \delta_k > 0$.

- Initialization for $t = 0$:
 - Sample $X_0^0, X_0^1, \dots, X_0^{\lambda_0} \sim \mu_0$; set $S_0 := \{X_0^0, \dots, X_0^{\lambda_0}\}$.
- Step: For $t := 1$ to k do
 - Sample $X_t^0 \sim \text{Unif}(S_{t-1})$
 - For $i := 1$ to λ_t do
 - * With probability $1 - \varepsilon$: Sample X_t^i **condit. indep.** $\sim p_t(X_t^{i-1}, \cdot)$
 - * With probability ε : **PROPOSE EQUI-ENERGY MOVE**
 - Sample $Y \sim \text{Unif}\{x \in S_{t-1} : |U_t(x) - U_t(X_t^{i-1})| < \delta_t\}$;
 - Sample $U \sim \text{Unif}(0, 1)$;
 - if $U < \min\left(1, \frac{\mu_t(Y)\mu_{t-1}(X_t^{i-1})}{\mu_t(X_t^{i-1})\mu_{t-1}(Y)}\right)$ then set $X_t^i := Y$;
 - else set $X_t^i := X_t^{i-1}$.
 - Set $S_t := \{X_t^0, \dots, X_t^{\lambda_t}\}$.

EQUI-ENERGY SAMPLER



- Sequential algorithm
- Adaptive MCMC method : Detailed Balance w.r.t. μ_t holds only in the limit as $\lambda_i \rightarrow \infty$ for $i < t$!

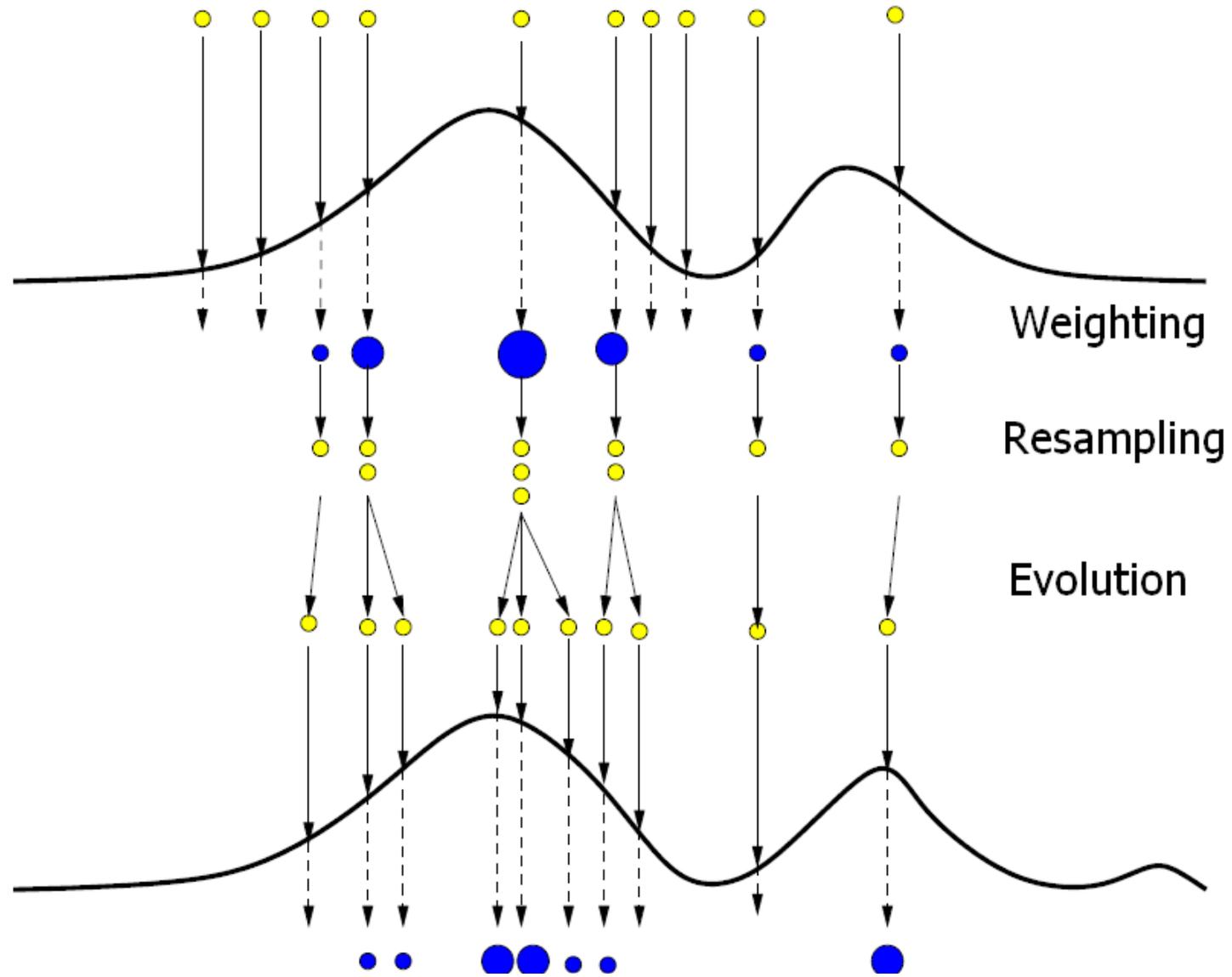
3 SEQUENTIAL MONTE CARLO SAMPLERS

P. Del Moral, A. Doucet, A. Jasra, J. R. Statist. Soc. B **68** (2006)

$\mu_0, \mu_1, \dots, \mu_k$ probability measures, $\lambda_0, \lambda_1, \dots, \lambda_k \in \mathbb{N}$,
 p_1, p_2, \dots, p_k Markov kernels s.t. $\mu_i p_i = \mu_{i+1}$

ALGORITHM (SMCMC with multinomial resampling).

- Initialization:
 - Sample X_0^i ($1 \leq i \leq N$) i.i.d. $\sim \mu_0$, set $\eta_0^N := N^{-1} \sum_{i=1}^N \delta_{X_0^i}$
- Step: For $t := 1$ to k do
 - **SIR**: Sample X_t^i i.i.d. $\sim \sum_{i=1}^N w_t^i \cdot \delta_{X_{t-1}^i}$, $w_t^i \propto \mu_t(X_{t-1}^i) / \mu_{t-1}(X_{t-1}^i)$
 - **MCMC**: For $m := 1$ to λ_t do
 - * Sample Y_t^i condit. indep. $\sim p_t(X_{t-1}^i, \cdot)$; set $X_t^i := Y_t^i$
 - Set $\eta_t^N := N^{-1} \sum_{i=1}^N \delta_{X_t^i}$



Related methods:

- *Parallel tempering*, Geyer (1991)
- *Equi-energy sampler*, Kou, Zhou, Wong, Annals of Statistics **34** (2006)

Good performance in various simulations, e.g. on Gaussian mixture models.

- Can we understand mathematically ?
- Can we even prove feasible quantitative bounds ?
- How to choose the interpolating probability measures ?
- How many MCMC moves per importance sampling/resampling step are required ?
- Dependence of error on structure of energy landscape ?

4 SMCMC IN CONTINUOUS TIME

[A.E., C. Marinelli 2009, 2010]

Aim : Sequential estimation / approximation of probability measures

$$\mu_t(x) \propto \exp\left(-\int_0^t H_s(x) ds\right) \mu(x)$$

on a finite state space S . W.l.o.g.

$$\langle H_s, \mu_s \rangle = 0.$$

Estimator :

$$\mu_t \approx \eta_t^N := \frac{1}{N} \sum_{i=1}^N \delta_{X_t^i}$$

THE PARTICLE SYSTEM $(X_t^i)_{1 \leq i \leq N}$:

- Independent Markov chain moves with generator $\lambda_t \cdot \mathcal{L}_t$
- X_t^i replaced by X_t^j with rate $\frac{1}{N} (H_t(X_t^i) - H_t(X_t^j))^+$

i.e., (X_t^1, \dots, X_t^N) is the Markov process on S^N with generator

$$\begin{aligned} \mathcal{L}_t^N \varphi(x_1, \dots, x_N) &= \lambda_t \sum_{i=1}^N \mathcal{L}_t^{(i)} \varphi(x_1, \dots, x_N) \\ &\quad + \frac{1}{N} \sum_{i,j=1}^N (H_t(x_i) - H_t(x_j))^+ \cdot (\varphi(x^{i \rightarrow j}) - \varphi(x)) \end{aligned}$$

$\lambda_t > 0$ constants, \mathcal{L}_t generator of a Markov process on S satisfying

$$\mu_t(x) \mathcal{L}_t(x, y) = \mu_t(y) \mathcal{L}_t(y, x) \quad \text{detailed balance,}$$

$\mathcal{L}_t^{(i)}$ action of \mathcal{L}_t on i th component.

SCALING LIMIT :

$$\begin{aligned}\frac{\partial}{\partial t} \mu_t &= -H_t \mu_t \\ &= \lambda_t \mathcal{L}_t^* \mu_t - H_t \mu_t + \langle H_t, \mu_t \rangle \mu_t\end{aligned}$$

η_t^N is a discretization of this equation:

$$\frac{\partial}{\partial t} \mathbb{E} [\langle f, \eta_t^N \rangle] = \mathbb{E} [\langle f, \lambda_t \mathcal{L}_t^* \eta_t^N - H_t \eta_t^N + \langle H_t, \eta_t^N \rangle \eta_t^N \rangle]$$

LLN / Scaling limit:

$$\eta_t^N \approx \mathbb{E}[\eta_t^N] \approx \mu_t \quad \text{for large } N.$$

5 QUANTITATIVE BOUNDS

- **LLN, CLT, EXPRESSION FOR ASYMPTOTIC VARIANCE:**
(for closely related particle system)

P. Del Moral, L. Miclo. Branching and Interacting Particle Systems Approx. of Feynman-Kac Formulae (2000)

M. Rousset. On the control of an interacting particle approximation of Schrödinger ground states. *SIAM J. Math. An.* **38(3)** (2006)

- **CLTs IN DISCRETE TIME:**

P. Del Moral. Feynman-Kac Formulae, Springer 2004

N. Chopin. CLT for sequential SMC methods and its application to Bayesian inference. *Annals of Statistics* **32 (6)** (2004)

H. R. Künsch. Recursive Monte Carlo Filters: Algorithms and Theoretical Analysis. *Annals of Statistics* **33(5)**: 1983-2021, 2004.

PROBLEMS:

- Implicit expression for asymptotic variance

↪ need L^p bounds for Feynman-Kac propagators

A.E., C. Marinelli. L^p estimates for Feynman-Kac propagators with time dependent reference measures, *J.Math.Anal.Appl.* 2009.

- Feasible bound for fixed number of particles ?

Under global mixing conditions:

A.E., C. Marinelli. Quantitative approximations of evolving probability measures and sequential MCMC methods, Preprint 2010.

AN UNBIASED ESTIMATOR:

$$\nu_t^N := \exp \left(- \int_0^t \langle H_s, \eta_s^N \rangle \right) \eta_t^N$$

THEOREM.

$$E [\langle f, \nu_t^N \rangle] = \langle f, \mu_t \rangle \quad \forall t \geq 0, f : S \rightarrow \mathbb{R}.$$

FEYNMAN-KAC PROPAGATOR:

Define $q_{s,t}f$ as solution of backward equation

$$\frac{\partial}{\partial s} q_{s,t}f = -\lambda_s \mathcal{L}_s q_{s,t}f - H_s q_{s,t}f, \quad q_{t,t}f = f,$$

Feynman-Kac representation:

$$q_{s,t}f(x) = \mathbb{E}_{s,x} \left[e^{-\int_s^t H_r(X_r) dr} f(X_t) \right],$$

where $(X_t, \mathbb{P}_{s,x})$ is Markov process with gen. $\lambda_t \mathcal{L}_t$ and init. cond. $X_s = x$.

Fix $q > 6$ and $p \in \left(\frac{4q}{q-2}, q \right)$.

THEOREM. Suppose that

$$N \geq \max(120 \cdot K_t, 80) \quad \text{and}$$

$$\lambda_s \geq \max\left(\frac{p}{4}A_s + \frac{p(p+3)}{4}tB_s, 35 \cdot \text{osc}(H_s) \cdot C_s\right) \quad \forall s \in [0, t].$$

Then

$$\begin{aligned} \text{Var} \left(\langle f, \nu_t^N \rangle \right)^{1/2} &\leq \left(\text{Var}_{\mu_t}(f) + V_t(f) + \|f\|_{L^p(\mu_t)}^2 \right)^{1/2} N^{-1/2} \\ &\quad + 40 \cdot K_t \cdot \|f\|_{L^p(\mu_t)} N^{-1} \end{aligned}$$

where

$$\begin{aligned} V_t(f) &= - \int_0^t \langle H_s(q_{s,t}f)^2, \mu_s \rangle + 2 \int \int |H_s(x)| (q_{s,t}f(y) - q_{s,t}f(x))^2 \mu_s(dx)\mu_s(dy) \\ &\leq 13 \cdot K_t \cdot \|f\|_{L^p(\mu_t)} \end{aligned}$$

CONSTANTS:

$$K_t = \int_0^t \|H_s\|_{L^q(\mu_s)} ds$$

$$A_t = \sup_{\langle f, \mu_t \rangle = 0} \frac{\int H_t f^2 d\mu_t}{\mathcal{E}_t(f, f)} \quad H\text{-Poincaré constant}$$

$$B_t = \sup_{\langle f, \mu_t \rangle = 0} \frac{|\int H_t f d\mu_t|^2}{\mathcal{E}_t(f, f)} \quad \text{modified } H\text{-Poincaré}$$

$$C_t = \sup_{\langle f^2, \mu_t \rangle = 1} \frac{\int f^2 \log f^2 d\mu_t}{\mathcal{E}_t(f, f)} \quad \text{Log-Sobolev constant}$$

COROLLARY. Similar estimates hold for

$$E [|\langle f, \eta_t^N \rangle - \langle f, \mu_t \rangle|]$$

EXAMPLE. (Moving Gaussians)

$$\mu_t = N(m_t, \sigma_t^2) \quad \text{on } [-r, r]^d, \quad \mathcal{L}_t = \text{Ornstein-Uhlenbeck generator}$$

Quantitative bounds depending on \dot{m}_t/m_t and $\dot{\sigma}_t/\sigma_t$.

6 OUTLOOK

OPEN PROBLEMS:

- Generalization to discrete time and continuous space
see PhD thesis of Nikolaus Schweizer
- Non-asymptotic bounds under **local** mixing conditions.

First step: Asymptotic bounds:

A.E., C. Marinelli. Stability of nonlinear flows of probability measures related to sequential MCMC methods.

Second step: Non-asymptotic analysis on trees:

PhD thesis of Nikolaus Schweizer

“Recipes” for applications

- Try to guarantee $\text{osc}(H_t) \leq 1$, or at least $\text{osc}(H_t^-) \leq 1$
- Use enough MCMC steps such that there is sufficient mixing in each metastable state
- Quality of error estimates depends (among other things) on structure of disconnectivity tree